



Bayesian Machine Learning

May 2022 - François HU
<https://curiousml.github.io/>

Outline

1 Bayesian statistics

2 Latent variable models

3 Variational Inference

4 **Markov Chain Monte Carlo**

- Monte Carlo Estimation

- MCMC and differences with VI

5 Extensions and oral presentations

1 Monte Carlo estimation

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Classic estimation methods

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$$\mathbb{E}[h(X)]$$

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$$\mathbb{P}(X > 2)$$

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Yes with usual simulations or MCMC

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Usual simulations : the power of uniform distribution

Starting point : we know how to simulate a pseudo-random uniform $U \sim \mathcal{U}(0,1)$

For « usual » distributions : both **discrete** and **continuous r.v.** can be sampled thanks to the uniform distribution

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| **Rejection sampling** algorithm.

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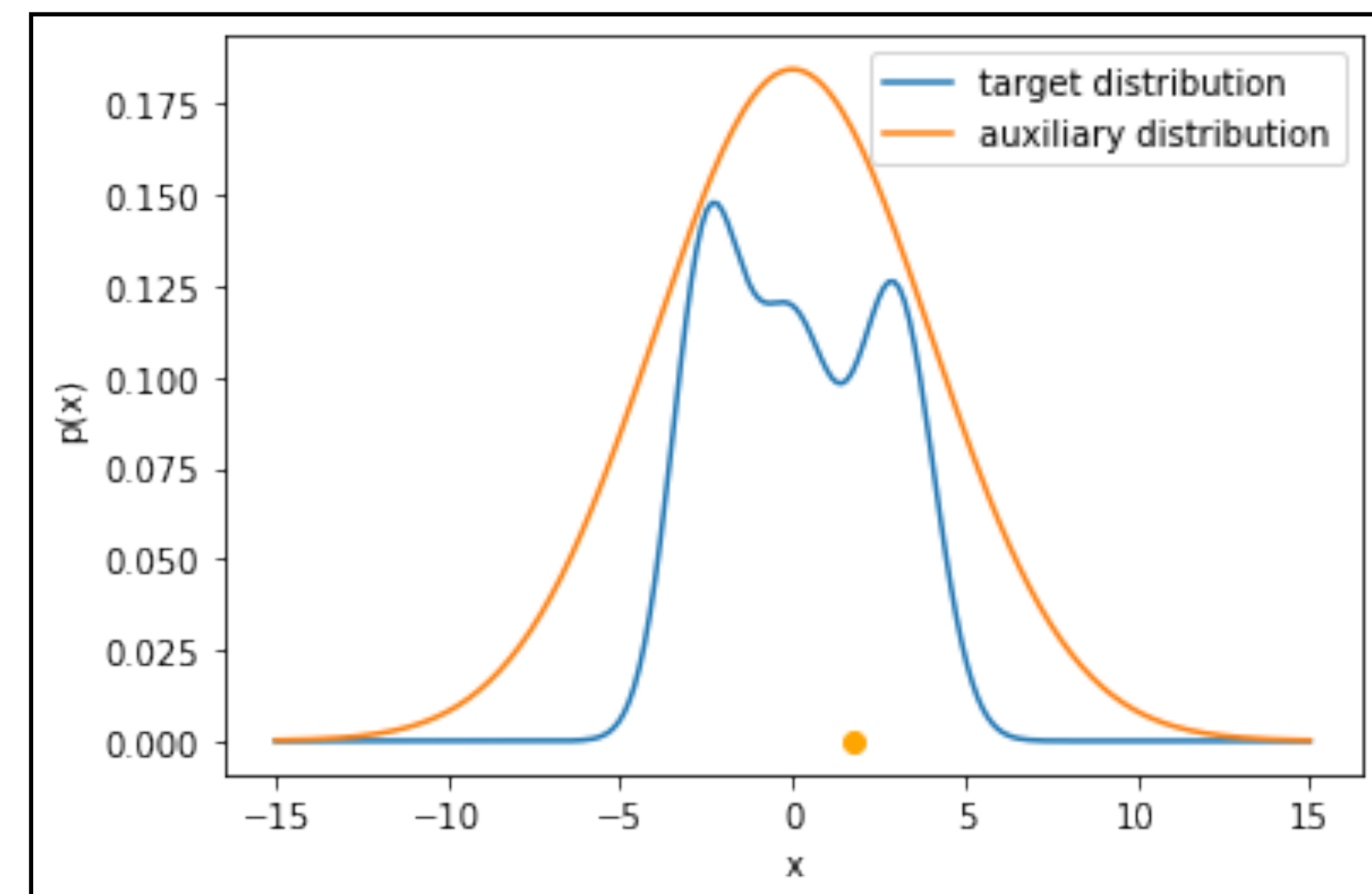
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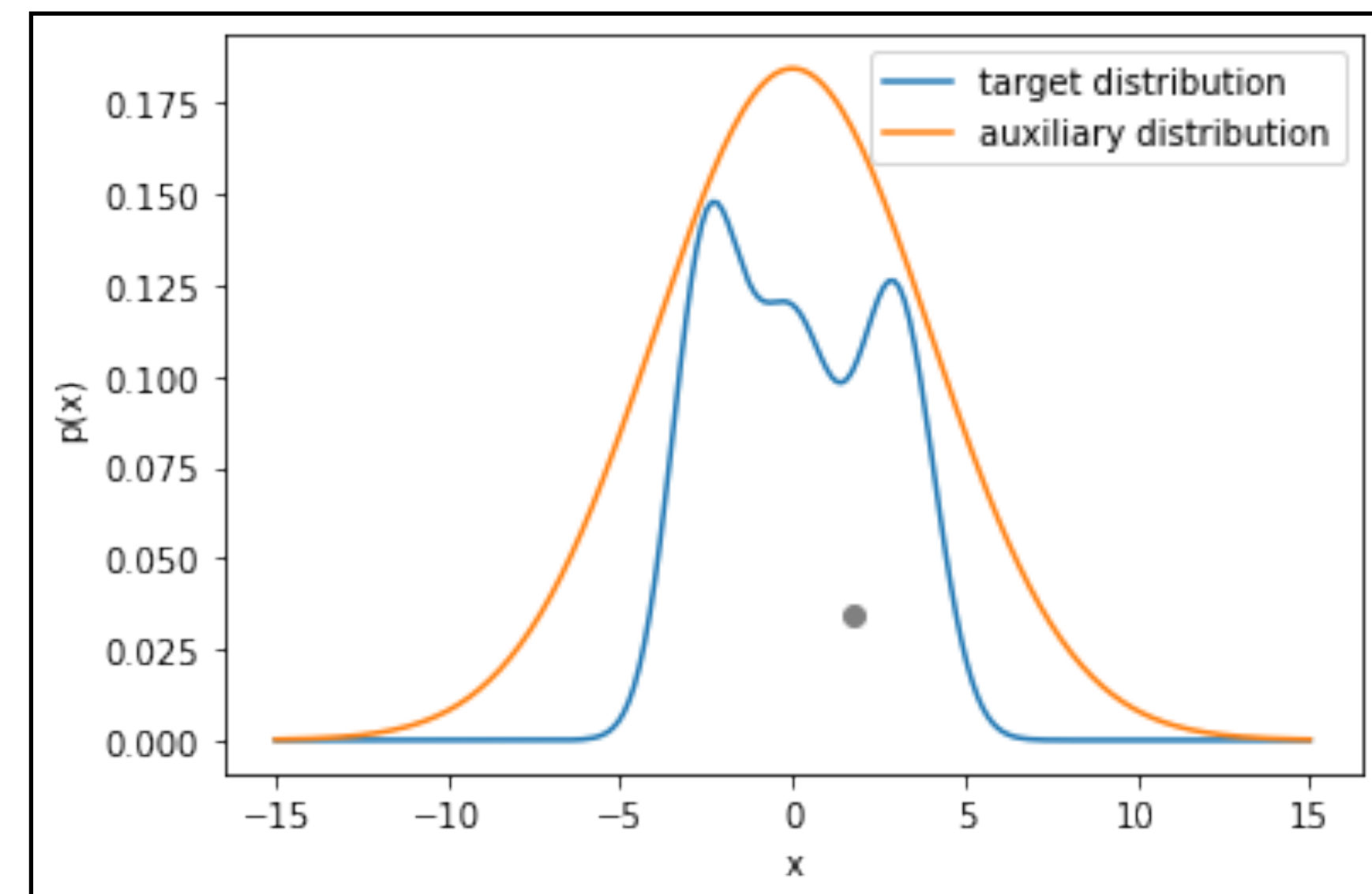
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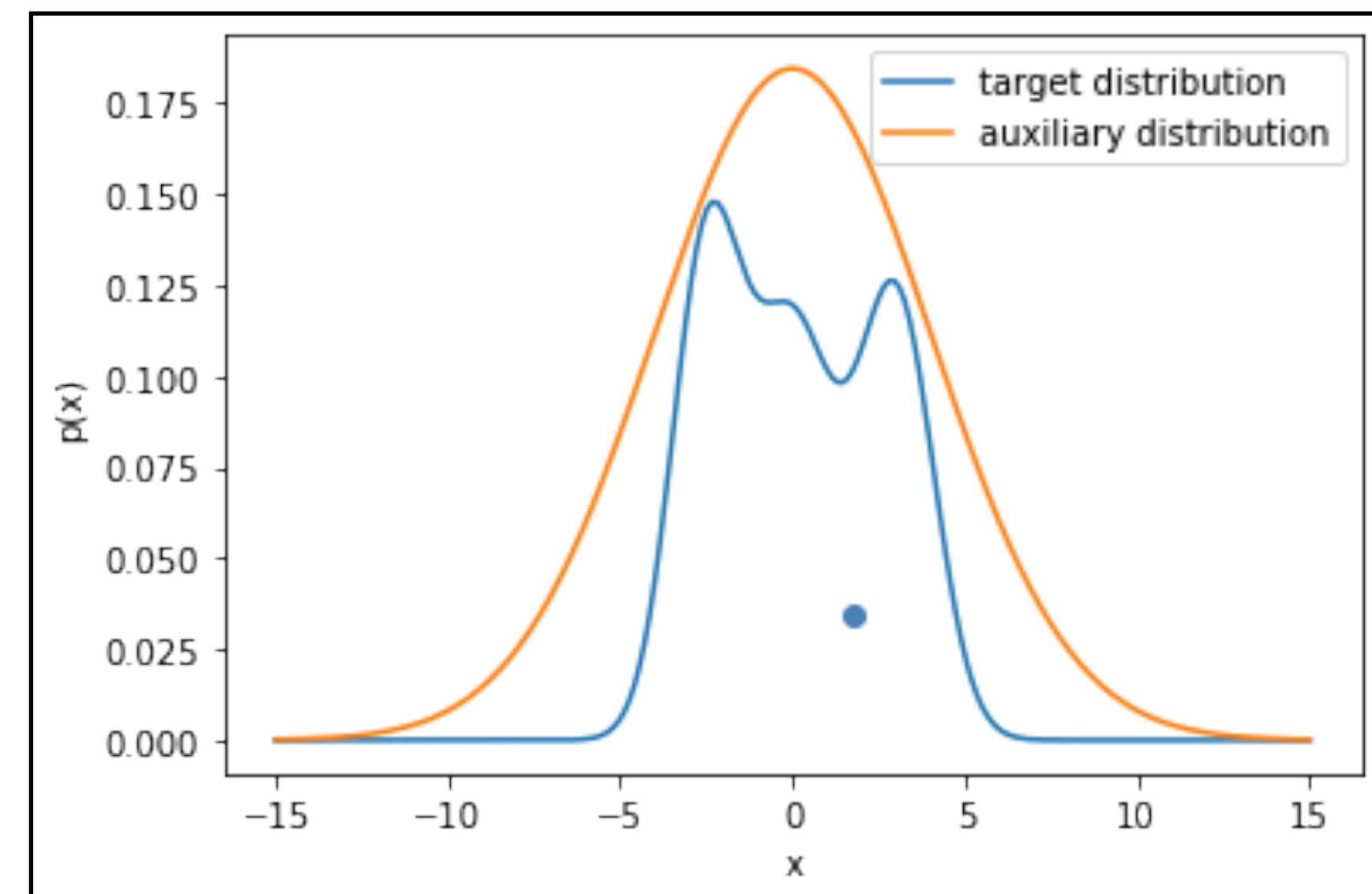
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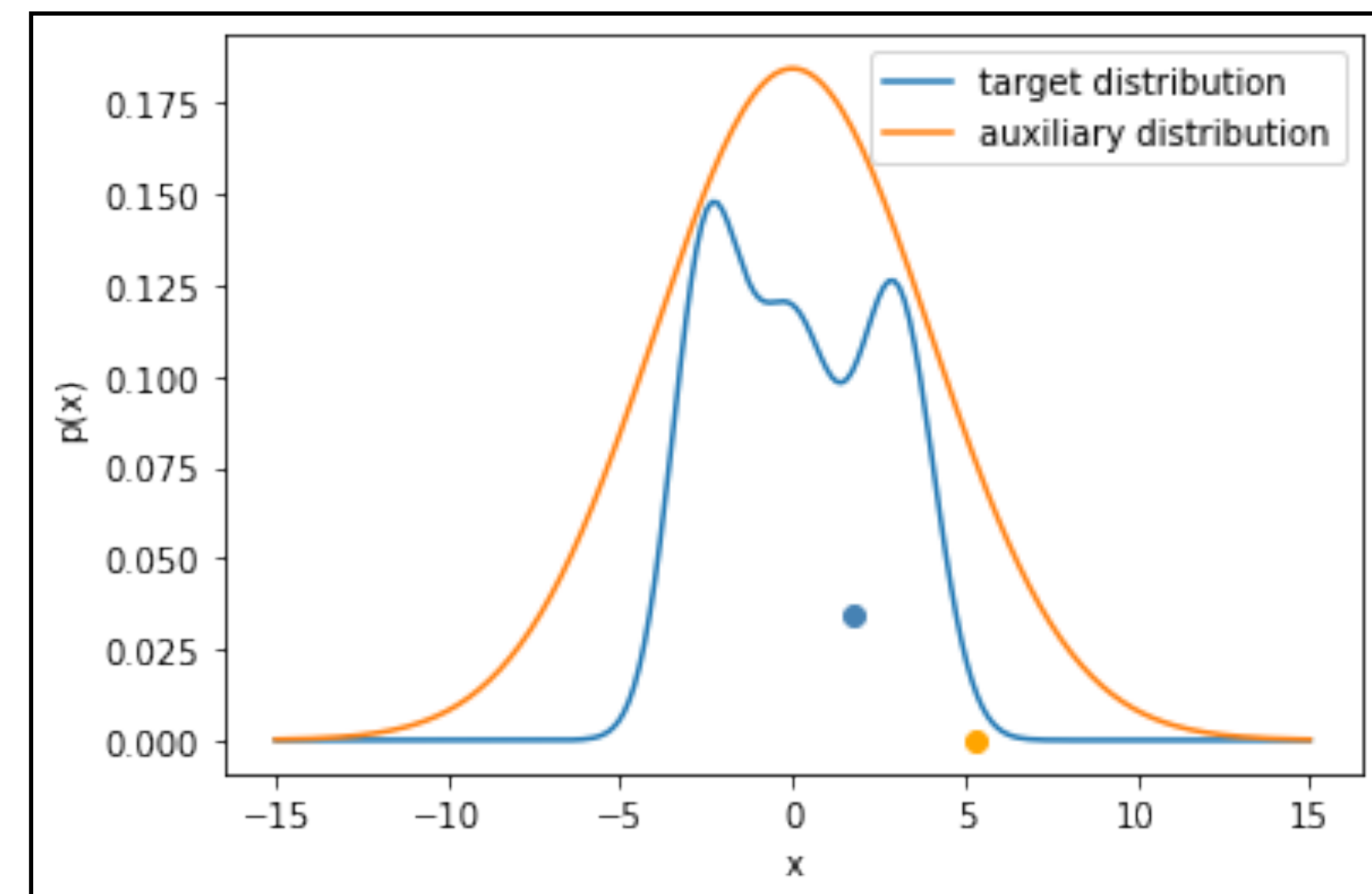
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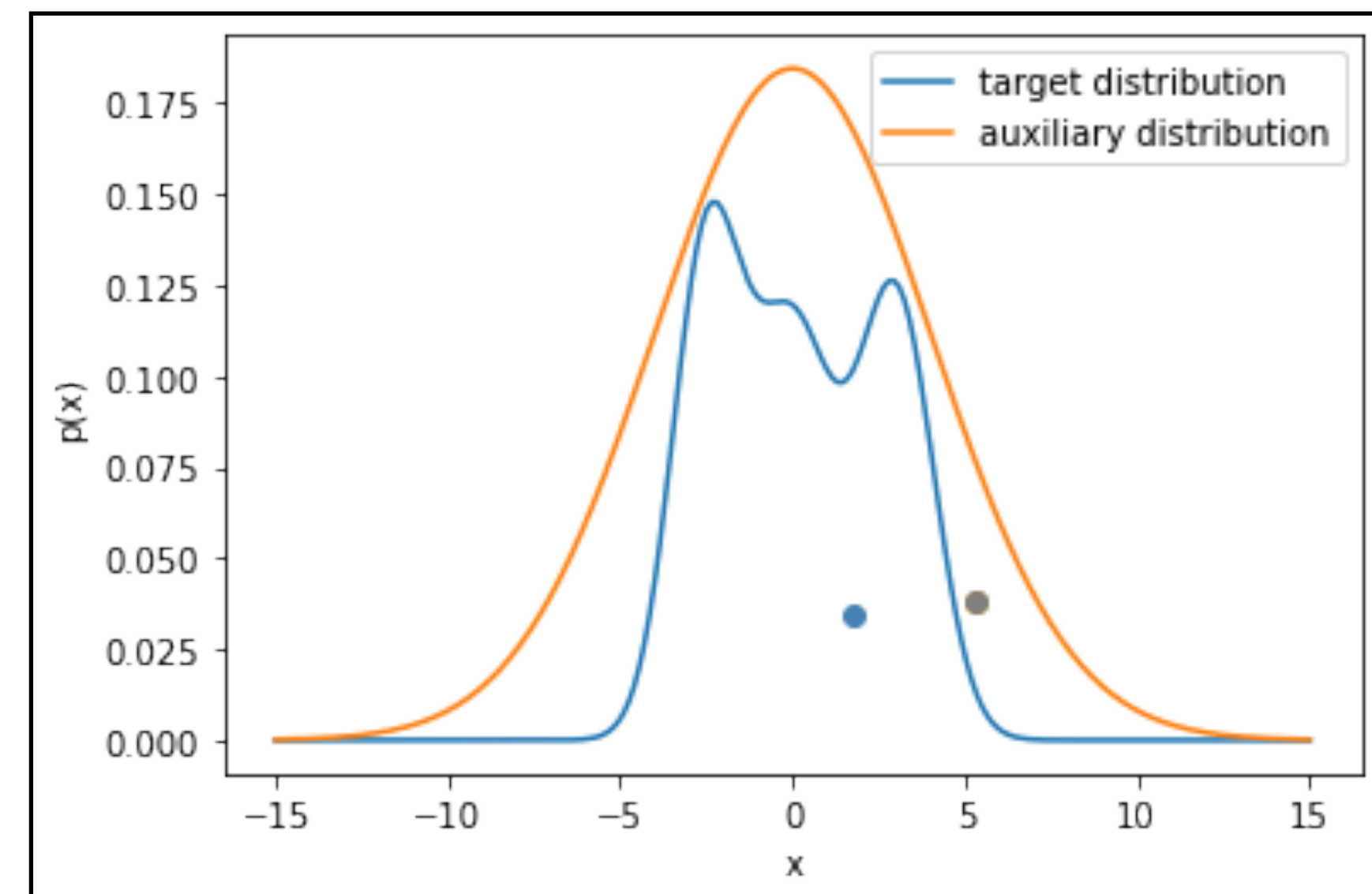
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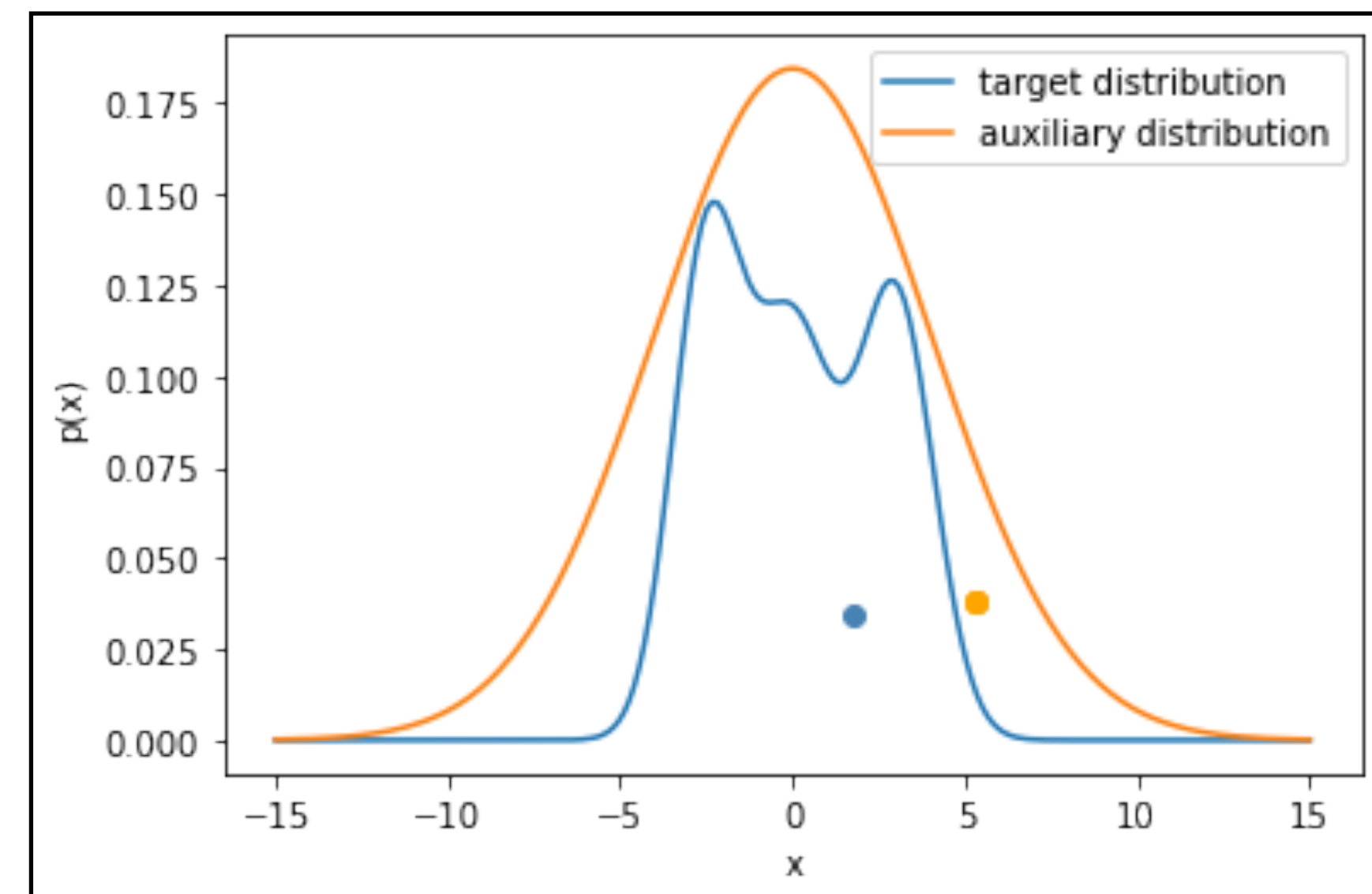
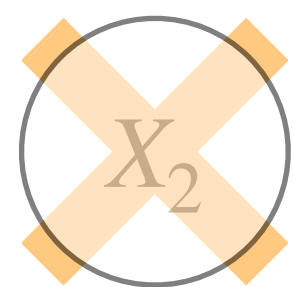
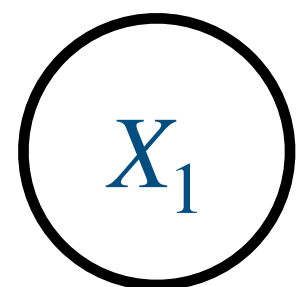
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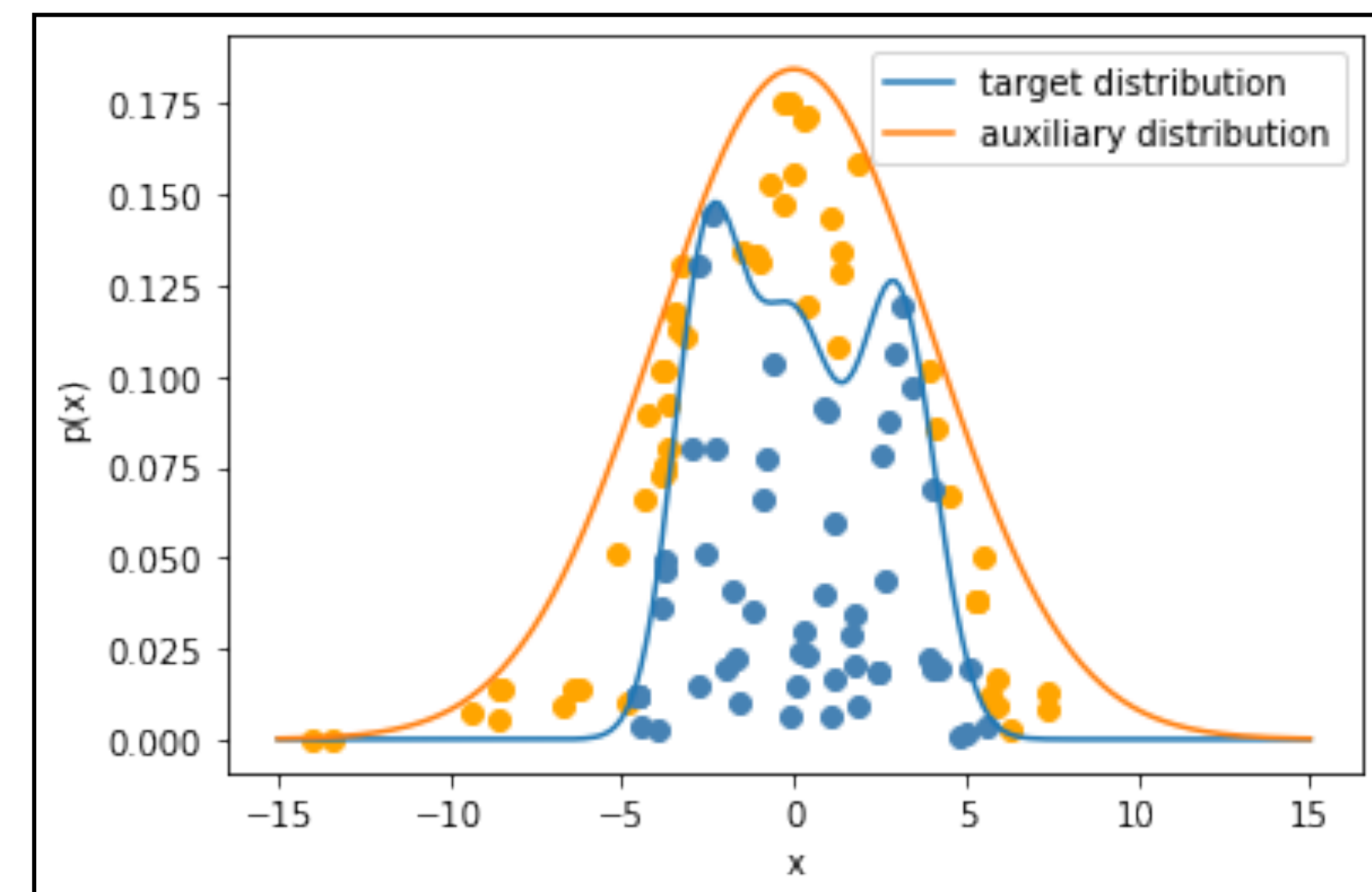
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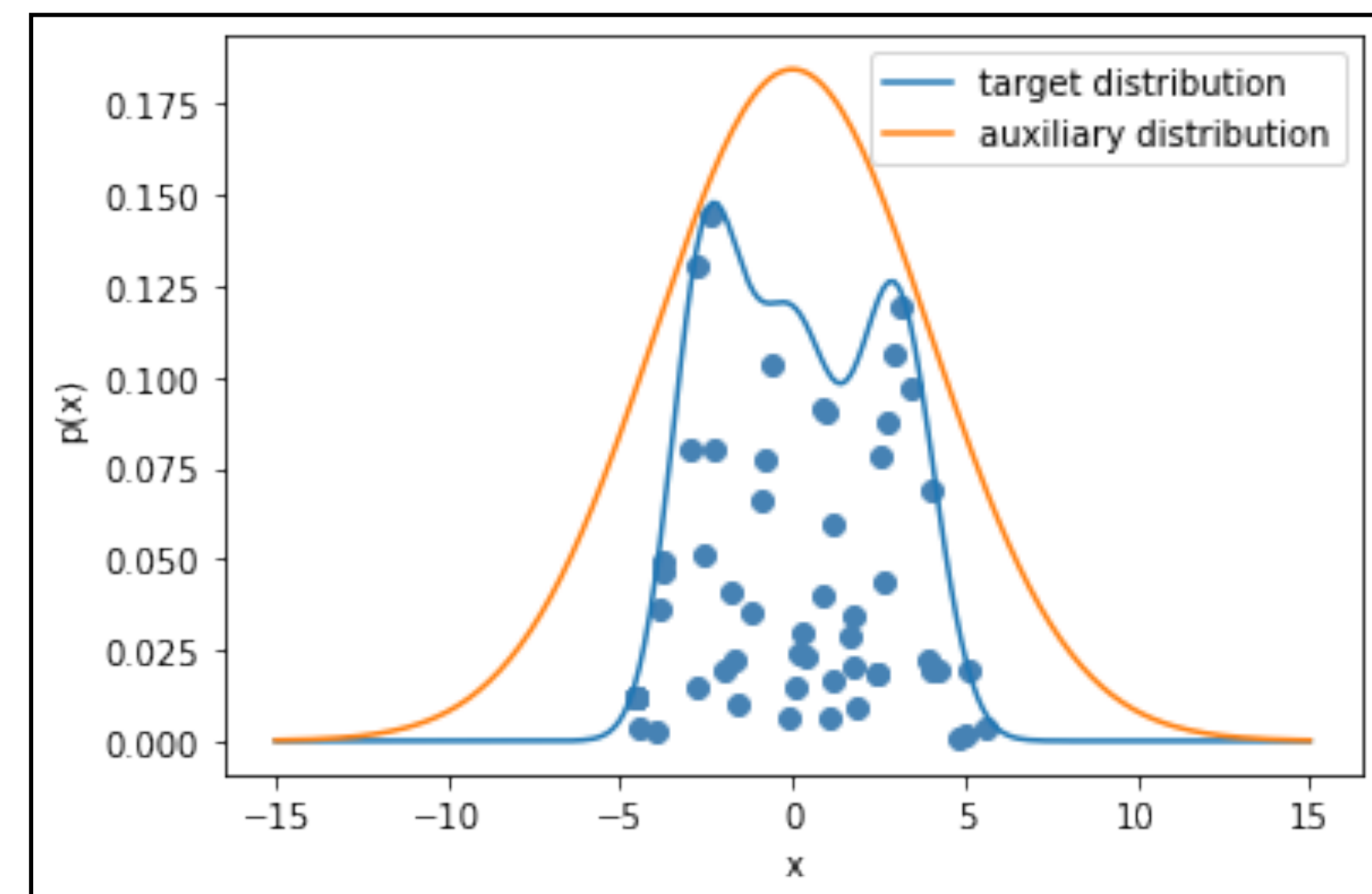
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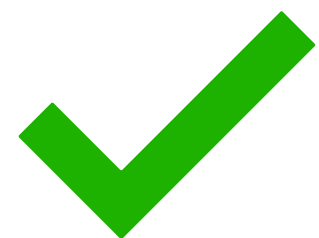
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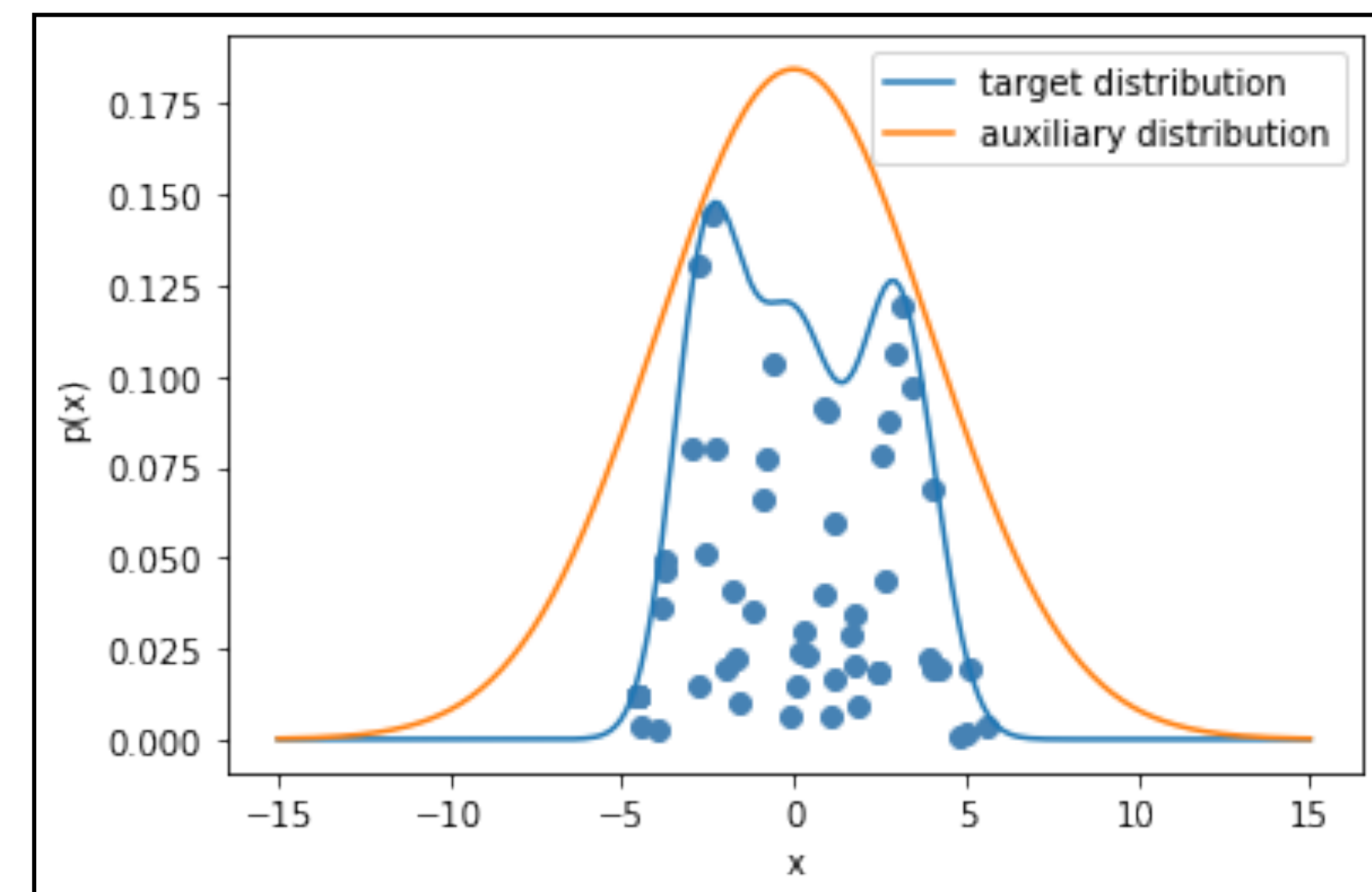
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works for most distribution



if the « **gaps** » between P and Q are too large, we reject most of the sample



X_1

X_2

...

X_n

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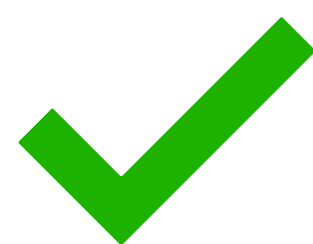
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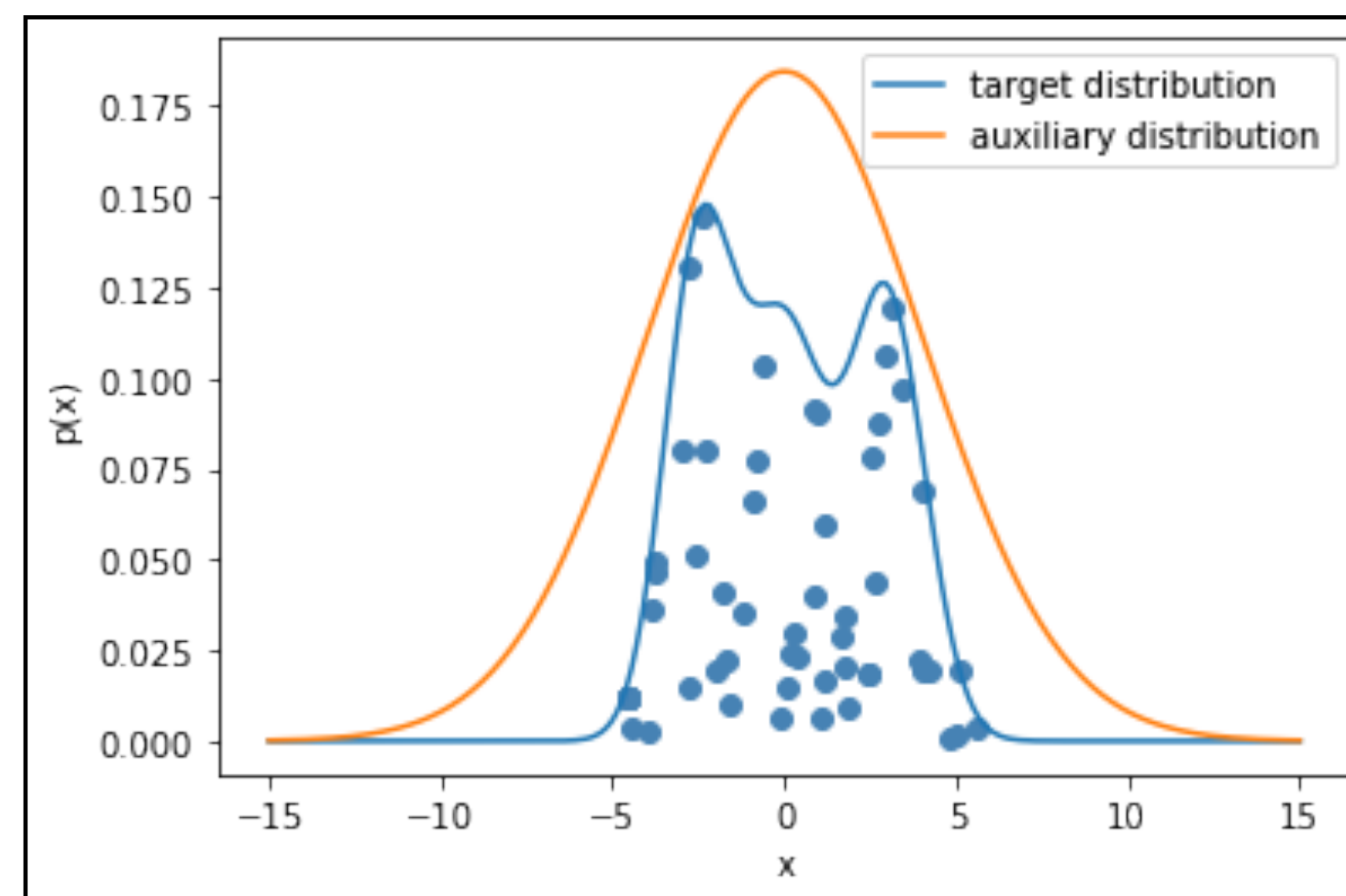


works for most distribution



if the « **gaps** » between P and Q are too large, we reject most of the sample

use MCMC



X_1

X_2

...


X_n

2 Markov Chain Monte Carlo : Definition

2. Markov Chain Monte Carlo

Definition : Monte Carlo sampling

Monte Carlo sampling : generates **independent** samples from the probability distribution in order to estimate an expected value



X_1

X_2

...

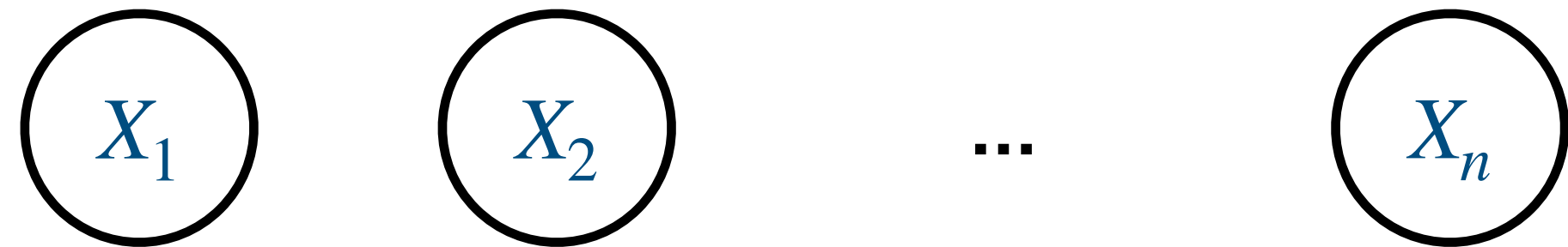
X_n

where $X_1, \dots, X_n \sim P$ i.i.d

2. Markov Chain Monte Carlo

Definition : Markov Chain

Monte Carlo sampling : generates **independent** samples from the probability distribution in order to estimate an expected value



where $X_1, \dots, X_n \sim P$ i.i.d

Markov Chain : generates a sequence of r.v. where the *next* variable is **probabilistically dependent** upon the *current* variable.

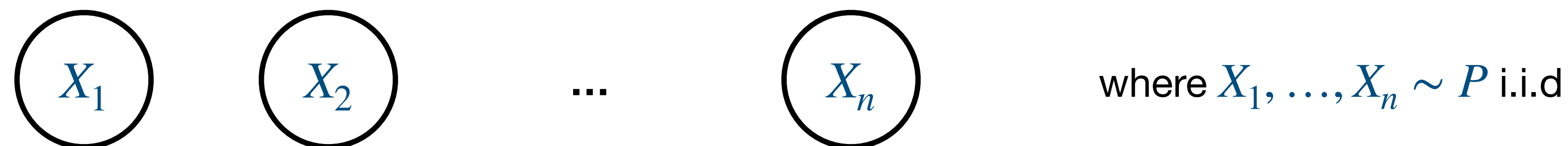
P is called **stationary** if $P(x') = \sum_{x \in \text{supp}(X)} T(x, x') \cdot P(x)$

$T(x, x')$ the transition probability of being in the state x' given the current state x

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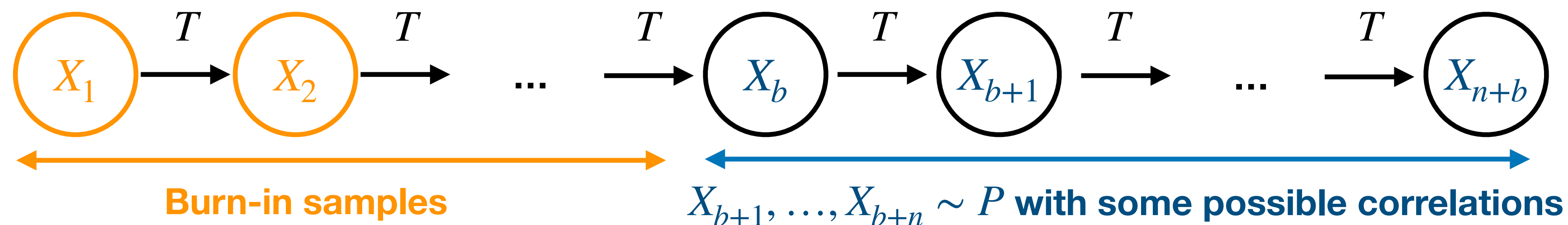


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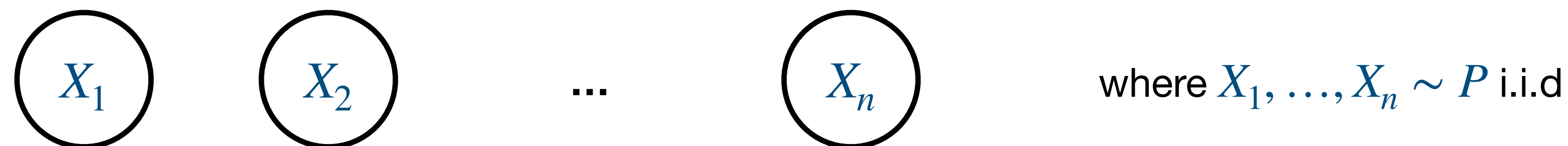
Markov Chain Monte Carlo sampling : a sequence of **Monte Carlo Samples** where the *next* sample is dependent upon the *current* sample



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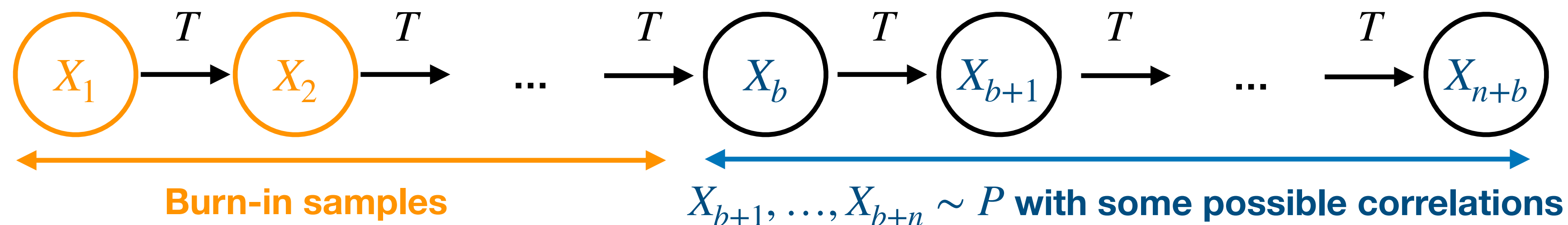


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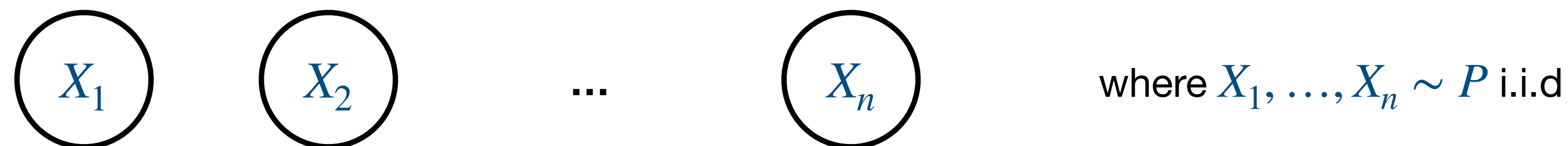


Objective : Build a Markov Chain that converges to the target distribution P no matter the starting point

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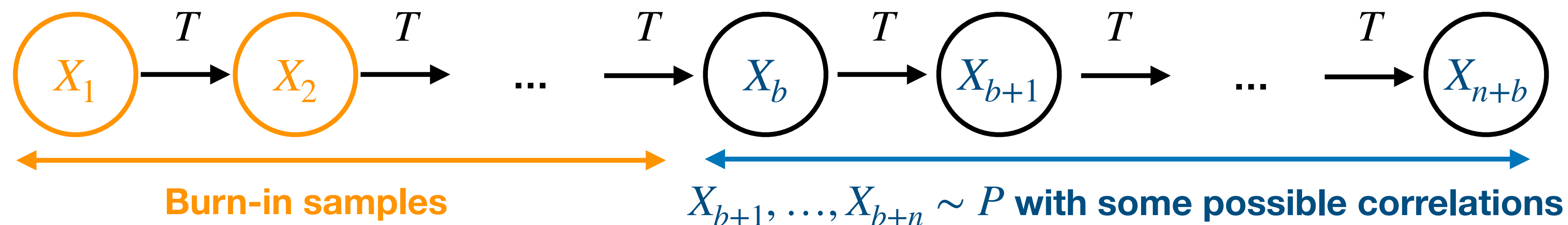


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Markov Chain Monte Carlo sampling : a sequence of **Monte Carlo Samples** where the *next* sample is dependent upon the *current* sample



Objective : Build a Markov Chain that converges to the target distribution P no matter the starting point

Theorem : if $T(x, x') > 0$ for all x, x' then there exists an *unique stationary* and **convergent** distribution

3 Markov Chain Monte Carlo : Algorithms

3. Markov Chain Monte Carlo

Algorithm : Gibbs sampling

Reminder : we want to sample $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

Remark : we denote $x^{(i)} := (x_1^{(i)}, \dots, x_d^{(i)})$; $x_{-j} = (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_d)$; $x_{m:n} = (x_m, x_{m+1}, \dots, x_n)$

Gibbs Sampling Algorithm

- **Hypothesis** : The conditional $P(x_j | x_{-j})$ can be sampled
- **Initialisation** : $x^{(0)} = (0, \dots, 0)$ or random values
- **Repeat** :

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$$x_1^{(i)} \sim P(x_1 | x_2^{(i-1)}, x_3^{(i-1)}, \dots, x_d^{(i-1)})$$

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...

$$x_d^{(i)} \sim P(x_d | x_2^{(i)}, x_3^{(i)}, \dots, x_d^{(i-1)})$$

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sometimes it can converge slowly to the desired distribution

sometimes Gibbs samples can be too correlated

3. Markov Chain Monte Carlo

Algorithm : Gibbs sampling

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sometimes it can converge slowly to the desired distribution

Use a variant Gibbs sampling : **Metropolis-Hastings**
sometimes Gibbs samples can be too correlated

3. Markov Chain Monte Carlo

Algorithm : Metropolis-Hastings

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Metropolis-Hastings Algorithm

- **Hypothesis** : Let $P = \hat{P}/\text{const}$ where \hat{P} can be calculated and let Q be an **auxiliary distribution** we can sample from
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3. Markov Chain Monte Carlo

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- **Repeat** :
 - sample a **candidate** $x^{(i)} \sim Q(x^{(i)} | x^{(i-1)}) = (\text{example of auxiliary distribution}) \mathcal{N}(x^{(i-1)}, \sigma^2 I)$

3. Markov Chain Monte Carlo

Algorithm : Metropolis-Hastings

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sample a **candidate** $x^{(i)} \sim Q(x^{(i)} | x^{(i-1)}) = (\text{example of auxiliary distribution}) \mathcal{N}(x^{(i-1)}, \sigma^2 I)$

with **acceptance probability** : $\min\left(1, \frac{Q(x^{(i-1)} | x^{(i)}) \times \hat{P}(x^{(i)})}{Q(x^{(i)} | x^{(i-1)}) \times \hat{P}(x^{(i-1)})}\right)$ accept $x^{(i)}$ as an sample from P

3. Markov Chain Monte Carlo

Algorithm : Metropolis-Hastings

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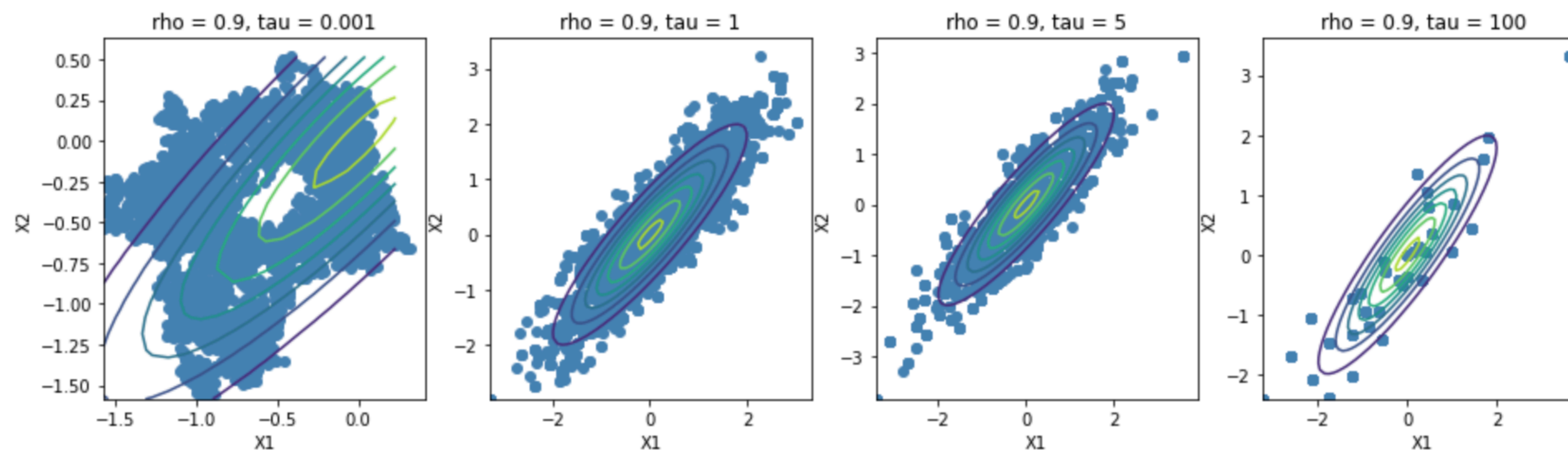
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$\tau = \sigma^2$ and ρ the correlation between two gaussians X_1 and X_2

3.b. MCMC vs VI

3.b. MCMC vs VI

pros and cons

MCMC

Pros :

- Useful when the posterior is intractable
- Asymptotically exact
- Suited to small / medium dataset

Cons :

- Usually slower than alternatives (VI)
- Can generate dependent samples from the distribution

VI (see lecture 3)

Pros :

- Useful when the posterior is intractable
- Suited to large dataset

Cons :

- Can never generate exact result

4 Applications : notebook



Road map



Bayesian statistics

1

Bayesian perspective :

$$P(\theta|X) = \frac{P(X, \theta)}{P(X)} = \frac{\overset{\text{Likelihood}}{P(X|\theta)} \cdot \overset{\text{Prior distribution}}{P(\theta)}}{\underset{\text{Evidence}}{P(X)}}$$

θ parameters
 X observations

Example :
Naive Bayes classifier,
Linear regression,

MAP : $\arg \max_{\theta} P(X|\theta) \cdot P(\theta)$
Conjugate distribution

- Pros :
- exact posterior

- Cons :
- conjugate prior maybe inadequate



Latent variable models

2

Hidden variable models :

$$P(X|\theta) = \sum_{t \in T_{indexes}} P(X, T = t | \theta)$$

$$P(X, T | \theta) = P(X | T, \theta) P(T | \theta)$$

Example :
GMM, K-means, PCA/PPCA

- Pros :
- fewer parameters / simpler models
 - hidden variable sometimes meaningful
 - clustering / dimensionality reduction

- Cons :
- harder to work with
 - requires math
 - only local maximum or saddle point
 - EM : the posterior of T could be intractable

Variational Inference

3

Deterministic approximation of posterior :

$$p(Z|X) = \frac{P(X|Z) \cdot P(Z)}{P(X)}$$

Mean Field Approximation !

Example :
Topic modelling, LDA trained by VI

- Pros :
- Useful when the posterior is intractable
 - Suited to large dataset

- Cons :
- can never generate exact result

4

Markov Chain Monte Carlo

Sampling techniques for estimate expected values :

$$\mathbb{E}_{p(x)} [h(x)] \approx \frac{1}{M} \sum_{s=1}^M f(x_s)$$

$f(x_s) \sim p(x)$ Gibbs sampling / Metropolis-Hastings !

Example :
Topic modelling, LDA trained by MCMC

- Pros :
- train / inference almost every probabilistic model
 - asymptotically exact
 - suited to small / medium dataset

- Cons :
- Usually slower than alternatives (VI)
 - can generates dependant samples from the distribution

Extensions

5

Oral presentations (20 points)

+

- Exercice 1 of lecture 1 : 0.5 bonus point
- Notebook 1 : 1 bonus point
- Notebook 2 : 2 bonus points
- Notebook 3 : 0.5 bonus point
- Notebook 4 : 1 bonus point
- Notebook 5 : 1 bonus point