

Efficient labeling with Active Learning

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Summary

1 Context

- Motivating application
- Notation
- Intuition

2 Active learning

- Uncertainty-based active learning
- Disagreement-based active learning
- More algorithms

3 Experimentations

- Data
- Active learning
- Mini-batch active learning

Motivating application

- Insurance organisations store **voluminous textual data** on a daily basis :
 - free text areas used by call center agents,
 - e-mails,
 - customer reviews,...
- These textual data are **valuable** and can be used in many use cases ...
 - optimize business processes,
 - analyze customer expectations and opinions,
 - control compliance (GDPR type) and fight against fraud, ...
- ... however
 - it is impossible for human experts to analyse all these quantities,
 - and the data usually comes **unlabelled**

Solution : exploit this large pool of unlabelled data with Active Learning

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Notation and goal

Notations :

- let \mathcal{X} be the instance space, \mathcal{Y} the label space and $\mathcal{H} : \mathcal{X} \rightarrow \mathcal{Y}$ a class of hypotheses with finite VC dimension d
- let \mathcal{P} be the distribution over $\mathcal{X} \times \mathcal{Y}$ and $\mathcal{P}_{\mathcal{X}}$ the marginal of \mathcal{P} over \mathcal{X} . **In practice** instead of $\mathcal{P}_{\mathcal{X}}$ we have a pool of unlabeled data $\mathcal{U} = (x_i^{(pool)})_{i=1}^U$

Goal : label a sub-sample of \mathcal{U} in order to construct an **optimal** training set $\mathcal{L} = \{(x_i^{(train)}, y_i^{(train)})\}_{i=1}^L$ for our learning algorithm \mathcal{A} (which give us $\hat{h} \in \mathcal{H}$)

For any $h \in \mathcal{H}$, define :

- **Risk** : $R(h) = \mathbb{P}(h(x) \neq y)$
- **Empirical risk** : $\hat{R}_{\{(x_i, y_i)\}_{i=1}^n}(h) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}(h(x_i) \neq y_i)$

Given a holdout set (or test set) $\mathcal{T} = \{(x_i^{(test)}, y_i^{(test)})\}_{i=1}^T$, our aim is to produce a highly-accurate classifier (i.e. **minimize** $\hat{R}_{\mathcal{T}}(\hat{h})$) using as few labels as possible.

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Passive Learning : a naive solution

Passive Learning : sample $x_i^{(train)}, \dots, x_L^{(train)}$ *i.i.d* $\sim \mathcal{P}_X$ then request their label

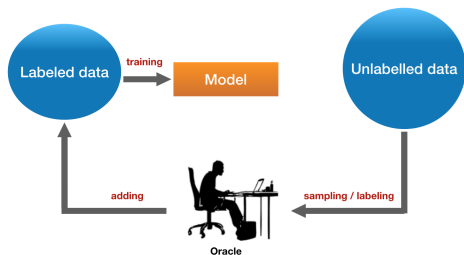


Figure: Conventional passive learning

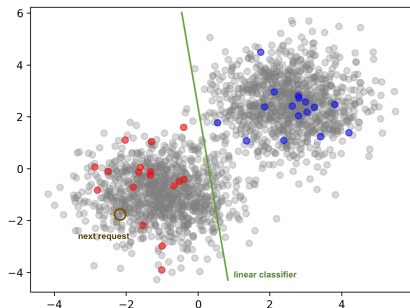


Figure: an illustration of passive learning

Active Learning : a better solution

Active Learning : Let a learning algorithm sequentially requests the labels of \mathcal{U}

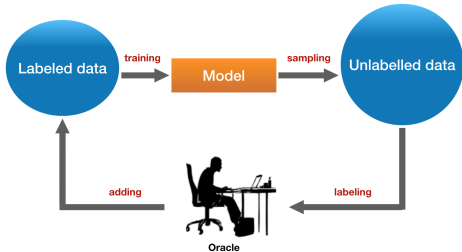


Figure: Conventional active learning

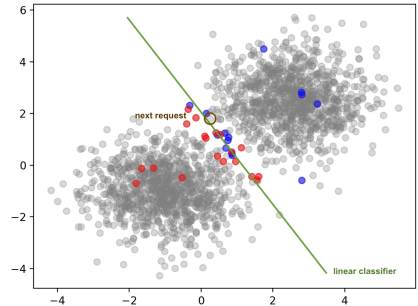


Figure: an illustration of active learning

Active Learning : a better solution

[Hanneke, 14] : Let h^* the optimal Bayes classifier and

$$\epsilon = R(\hat{h}) - R(h^*)$$

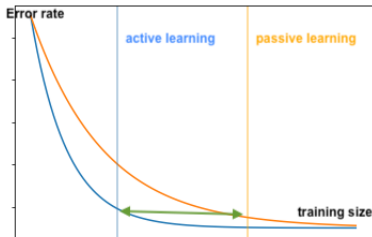
Then under a given hypothesis (bounded noise) and active learning algorithm (A^2)

- passive learning :

$$\epsilon \sim \frac{d}{n}$$

- active learning :

$$\epsilon \sim \exp\left(-\text{constant} \cdot \frac{n}{d}\right)$$



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Uncertainty Sampling

Uncertainty Sampling : label the instances for which the current model is least certain as to what the correct output should be.

Example : for binary classification, label the instances whose posterior probability of being positive is nearest 0.5 :

$$x^{(train)} = \arg \min_{x \in \mathcal{U}} \{|P(y = 1|x) - 0.5|\}$$

Entropy-based active learning [Lewis and Gale, 94] :

$$x_H^{(train)} = \arg \max_{x \in \mathcal{U}} \left\{ - \sum_{y \in Y} P(y|x) \log P(y|x) \right\}$$

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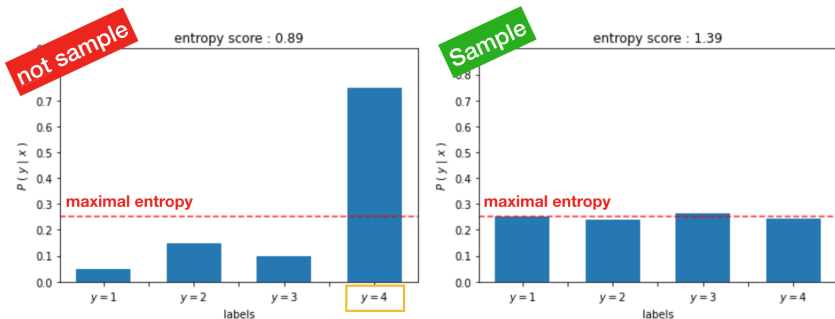


Figure: Entropy score for two instances : x (left) and x' (right)

Query By Committee

Query By Committee (QBC): construct a committee of models $C = \{\hat{h}_1, \dots, \hat{h}_N\}$ trained on the current labeled data \mathcal{L} . Here, the most informative query is the instance about which the "committee" disagrees the most

- **The committee** $C = \{\hat{h}_1, \dots, \hat{h}_N\}$:

Query by bagging (Qbag) [Abe and Mamitsuka, 98] : Bootstrap N times \mathcal{L} then train a learning algorithm on each bootstrapped data

- **Measure of disagreement** :

Average Kullback Leibler divergence [MacCallum and Nigam, 98] :

$$x_{KL}^{(train)} = \arg \max_{x \in \mathcal{U}} \left\{ \frac{1}{N} \sum_{i=1}^N D(P_{\hat{h}_i} \| P_{committee}) \right\}$$

where

- $D(P_{\hat{h}_i} \| P_{committee}) = \sum_{y \in \mathcal{Y}} P_{\hat{h}_i}(y|x) \log \left\{ \frac{P_{\hat{h}_i}(y|x)}{P_{committee}(y|x)} \right\}$ and
- $P_{committee}(y|x) = \frac{1}{N} \sum_i P_{\hat{h}_i}(y|x)$

Query By Committee

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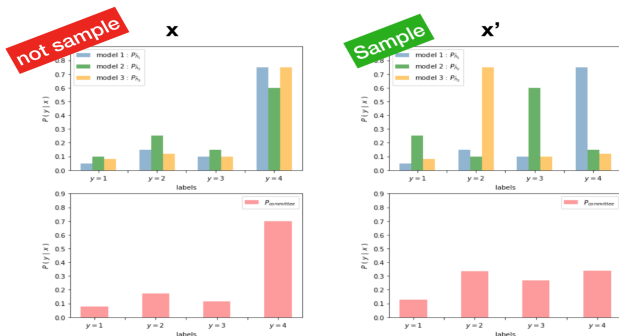


Figure: Distribution of the committee for two instances : x (left) and x' (right)

Other types of Active Learning

- Another disagreement-based active learning : **Agnostic Active Learning** (A^2) [Hanneke, 14]
- **Expected Model Change** : Sample instances that would impact the greatest change to the current model if we knew its label (example : "expected gradient length" (EGL) [Settles et al, 08])
- **Expected Error Reduction** : Sample instances that would make its generalization error likely to be reduced
- **Density Weighted Sampling** [Settles and Craven, 08] :

$$x_{density}^{(train)} = \arg \max_{x \in \mathcal{U}} \left\{ \phi_A(x) \times \left(\frac{1}{U} \sum_{x' \in \mathcal{U}} sim(x, x') \right)^\beta \right\}$$

with ϕ_A a measure of informativeness of x according to some sampling strategy A (uncertainty sampling, QBC, ...)

Experimentations

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Text data : Net Promoter Score (NPS)

About the data : Net Promoter Score

- 1 **Score** : the client's score of an insurance product (score between 0 and 10)
- 2 **Verbatim** : explanation (in french) of the score by the client

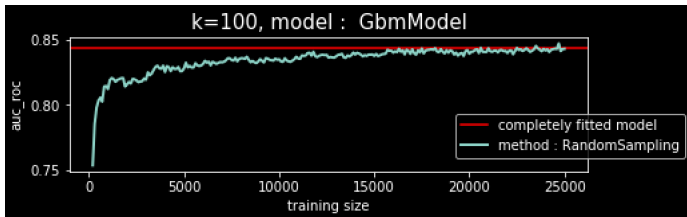
Encoding the text data : word2vec [Mikolov 2013]

Sentiment analysis : $Y = \{0, 1\} = \{\text{score} \leq 6, \text{score} > 6\}$

Mini-batch sampling algorithm : until we reach a stopping criterion,

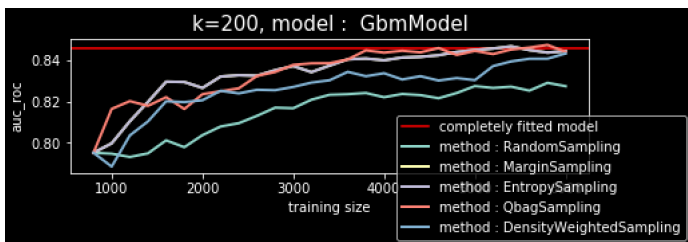
- 1 train our model \hat{h} on the training set \mathcal{L}
- 2 select the k most informative samples $x_1^{(train)}, \dots, x_k^{(train)}$ from the pool set \mathcal{U}
- 3 $\mathcal{U} \leftarrow \mathcal{U} - \{x_1^{(train)}, \dots, x_k^{(train)}\}$ and $\mathcal{L} \leftarrow \mathcal{L} \cup \{x_1^{(train)}, \dots, x_k^{(train)}\}$

Passive Learning



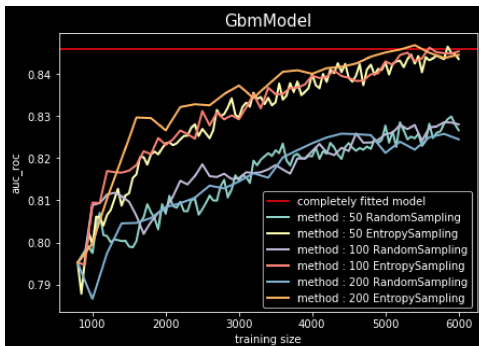
- Learning model : XGBoost
- Sampling strategy : random sampling
- Initial training size / mini batch size : 200 / 100
- Stopping criterion : 25 000

Active Learning



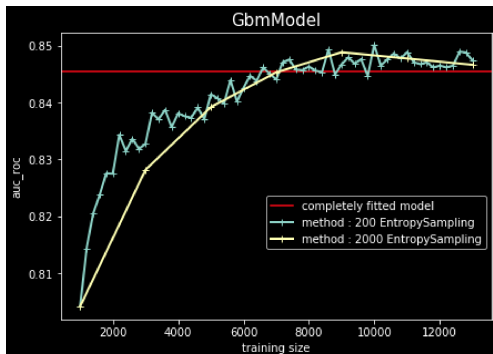
- Learning model : XGBoost
- Sampling strategy : random sampling
 - uncertainty-based sampling (Entropy, Margin)
 - disagreement-based sampling (Qbag)
 - density-based sampling (DensityWeighted)
- Initial training size / mini batch size : 800 / 200
- Stopping criterion : 6 000

Mini-batch active learning



- Learning model : XGBoost
- Sampling strategy :
 - random sampling
 - entropy sampling
- Initial training size / mini batch size : 800 / (50, 100, 200)
- Stopping criterion : 6 000

Mini-batch active learning



- **Learning model** : XGBoost
- **Sampling strategy** : entropy sampling
- **Initial training size / mini batch size** : 1000 / (200, 2000)
- **Stopping criterion** : 13 000

Conclusion

For real text database :

- Construct a good classifier if the labeled data is available ;
⇒ Power many use cases
- Compared to passive learning, active sampling can construct a more highly-accurate classifier ;
⇒ Reduce the cost of annotation (here at least 4 times)
- In this context : the mini-batch size can vary between 1 and 2000.
⇒ Speed up the annotation process

References

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